



**TEAM VARUNA**

**ROV**

**SRI SAIRAM COLLEGE OF  
ENGINEERING**

## Technical Specifications Physical

Length	500 mm
Width	400 mm
Height	300 mm
Weight in Air	12-13 kg
Net Buoyancy	0.3 kg
Watertight Enclosure Inner Diameter	100 mm
Watertight Enclosure Inner Length	280 mm
Mainframe	Aluminum 6061 T6
Side Frame	High Density Poly-Ethylene
Electronic enclosure	4" Acrylic Tube 5mm thick with Aluminum End caps
Battery Enclosure	4" Acrylic Tube 5mm thick with Aluminum End caps

## Battery

Lithium-ion Battery (14.8V, 18Ah)

Battery Life :2-3 hours w/ 18Ah battery

Battery Life :4-6 hours w/ 18Ah battery

## Performance

Maximum Rated Depth	100 m
Maximum Tested Depth (so far)	50m
Maximum Forward Speed	1 m/s
Thrusters	Blue Robotics T200

ESC	Blue Robotics Basic 30A ESC
Thruster Configuration	6 thrusters 4 vectored , 2 Vertical
Forward Bollard Thrust	14 kgf
Vertical Bollard Thrust	9 kgf
Lateral Bollard Thrust	14 kgf

## Electronics

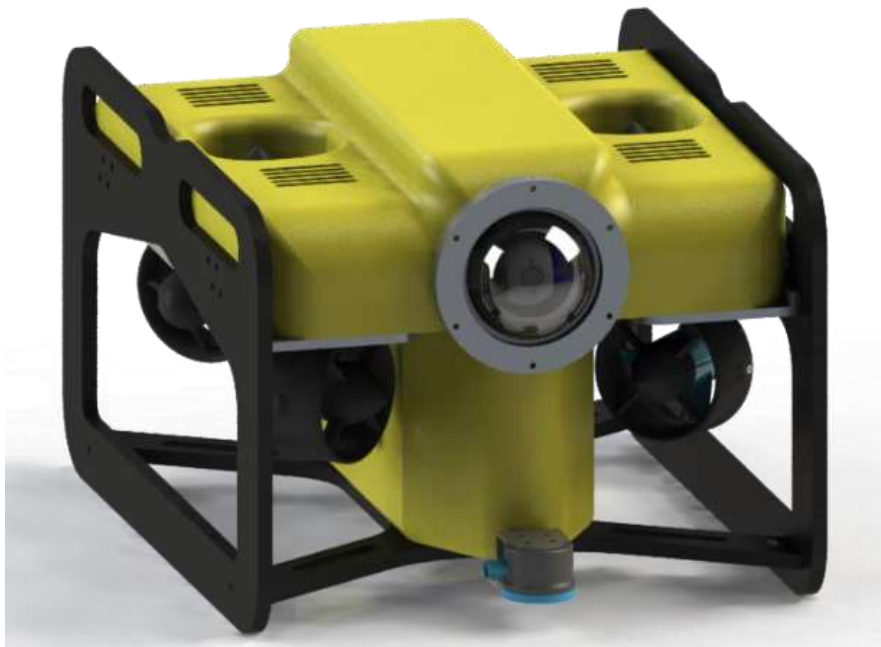
- Raspberry pi Model 3B
- Pixhawk 2.4.8
- Arduino Mega 2560
- Raspberry- Pi Camera/Low Light HD camera
- Ping sonar
- Google Coral Development Board

## CAD MODELLING & FABRICATION

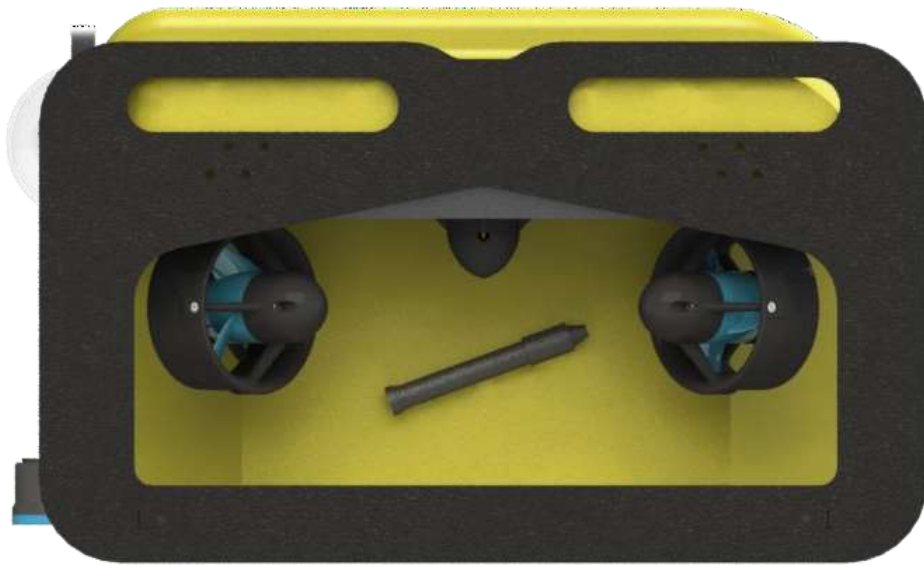
### CAD MODELING



Front View of AUV



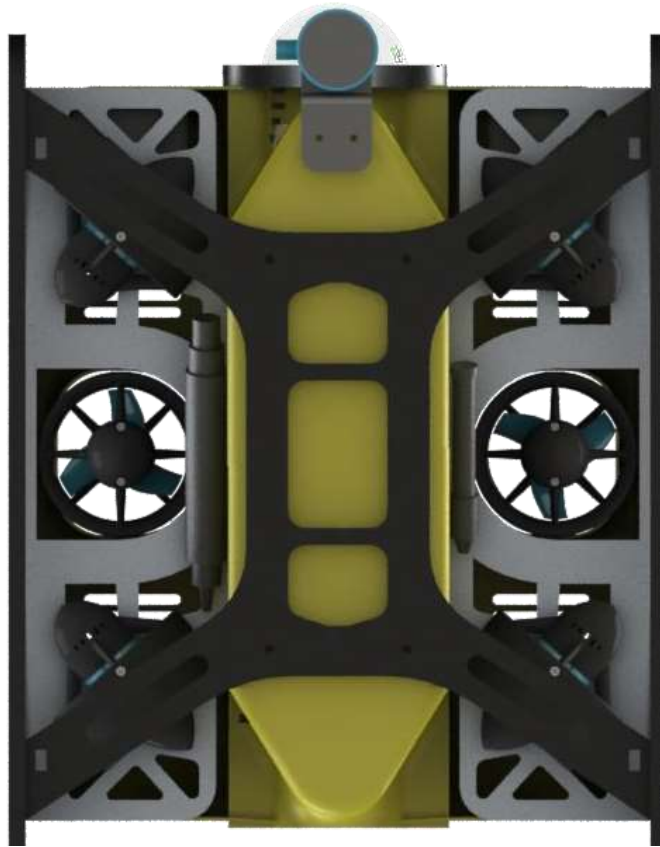
Isometric View of AUV



**Side View of AUV**

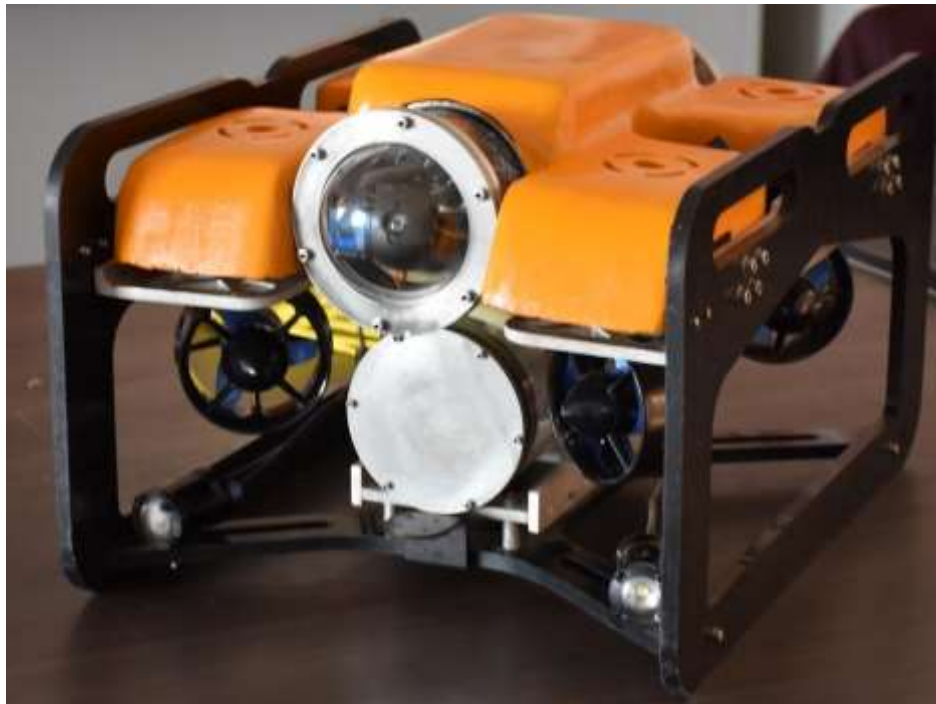


**Top View of AUV**



**Front View of AUV**

**FABRICATED MODEL**



**Isometric View of AUV**



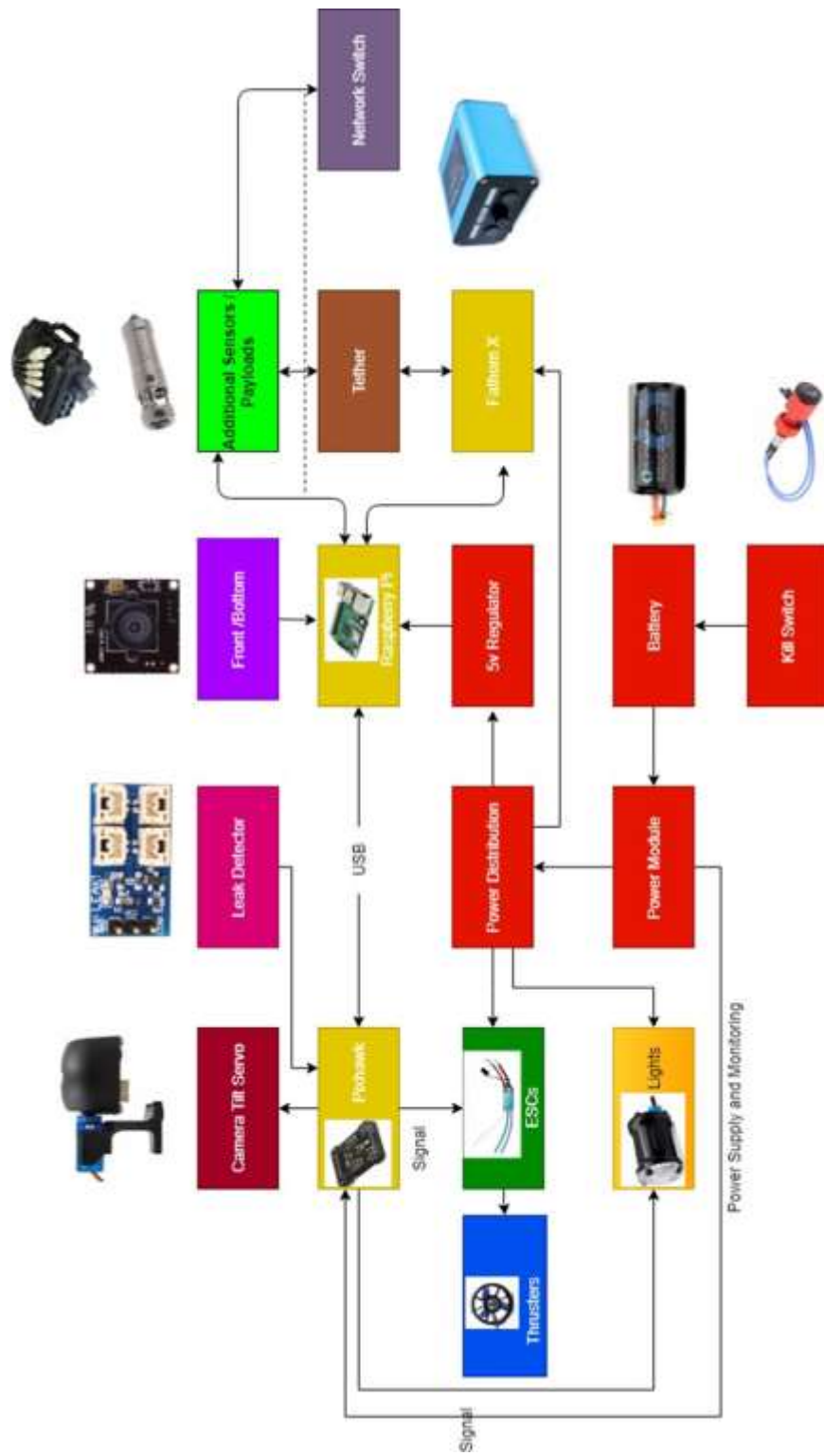
400mm

FrontView of AUV



500mm

Sideview of AUV



**Basic Architecture**